

Instruction and operation manual



S450

Thermal mass flow sensor for heavy duty industries



Dear Customer,

Thank you for choosing our product.

Please read this manual in full before starting up the device and carefully observe the instructions stated. The manufacturer cannot be held liable for any damage which occurs as a result of non-observance or non-compliance with this manual.

Should the device be tampered with in any manner other than a procedure which is described and specified in the manual, the warranty is void and the manufacturer is exempt from liability.

The device is destined exclusively for the described application.

SUTO offers no guarantee for the suitability for any other purpose. SUTO is also not liable for consequential damage resulting from the delivery, capability or use of this device.

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1 Safety instructions



Please check if this instruction manual matches the product type.

Please observe all notes and instructions indicated in this manual. It contains essential information which must be observed before and during installation, operation and maintenance. Therefore this instruction manual must be read carefully by the technician as well as by the responsible user or qualified personnel.

This instruction manual must be available at the operation site of the flow sensor at any time. In case of any obscurities or questions, regarding this manual or the product, please contact the manufacturer.



WARNING!

Compressed air!

Any contact with quickly escaping air or bursting parts of the compressed air system can lead to serious injuries or even death!

- Do not exceed the maximum permitted pressure range (see sensors label).
- Only use pressure tight installation material.
- Avoid that persons get hit escaping air or bursting parts of the instrument.
- The system must be pressureless during maintenance work.



WARNING!

Voltage used for supply!

Any contact with energized parts of the product, may lead to an electrical shock which can lead to serious injuries or even death!

- Consider all regulations for electrical installations.
- The system must be disconnected from any power supply during maintenance work.
- Any electrical work on the system is only allowed by authorized qualified personal.

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ATTENTION!

Permitted operating parameters!

Observe the permitted operating parameters, any operation exceeding this parameters can lead to malfunctions and may lead to damage on the instrument or the system.

- Do not exceed the permitted operating parameters.
- Make sure the product is operated in its permitted limitations.
- Do not exceed or undercut the permitted storage and operation temperature and pressure.
- The product should be maintained and calibrated frequently, at least annually.

General safety instructions

- It is allowed to use the product in explosive areas. Please contact the manufacturer.
- Please observe the national regulations before/during installation and operation.

Remarks

- It is not allowed to disassemble the product.
- Always use spanner to mount the product properly.



ATTENTION!

Measurement values can be affected by malfunction!

The product must be installed properly and frequently maintained, otherwise it may lead to wrong measurement values, which can lead to wrong results.

- Always observe the direction of the flow when installing the sensor. The direction is indicated on the housing.
- Do not exceed the maximum operation temperature at the sensors tip.
- Avoid condensation on the sensor element as this will affect the accuracy enormously.



Storage and transportation

- Make sure that the transportation temperature of the sensor without display is between -30 ... +70°C and with display between -10 ... +60°C.
- For transportation it is recommended to use the packaging which comes with the sensor.
- Please make sure that the storage temperature of the sensor is between -10 ... +50°C.
- Avoid direct UV and solar radiation during storage.
- For the storage the humidity must be <90% with no condensation.

2 Registered trademarks

SUTO [®]	Registered trademark of SUTO iTEC
MODBUS®	Registered trademark of the Modbus Organization, Hopkinton, USA
HART [®]	Registered trademark of the HART Communication Foundation, Austin, USA
PROFIBUS®	Registered trademark of the PROFIBUS User Organization, Karlsruhe, Germany
Android™, Google Play	Trademarks of Google LLC



3 Application

The S450 flow sensor is designed for the explosive areas and is mainly used to measure compressed air and process gases in industrial environments.

The S450 can measure the following parameters for the compressed air or gases:

- Velocity
- · Volume flow
- Total consumption

The default factory settings are: Velocity in m/s, Volume flow in m³/h and Total Consumption in m³. Other units can be programmed by the optional display or the service kit.

4 Features

- Direct measurement of mass flow and standard flow without the need of pressure and temperature compensation.
- Insertion type for bigger pipes.
- No moving parts, no clogging.
- All Sensor parts which come into contact with the measurement medium are made of stainless steel 316L.
- Robust metal enclosure suitable for outdoor applications in harsh environments.
- · Wireless Bluetooth interface for onsite sensor settings.
- Optional display showing flow rate, consumption, medium temperature and diagnostic result.



5 Technical data

5.1 General

C€				
Measuring range	0.4 92.7 sm/s (standard range calibration) 0.8 185 sm/s (max range calibration) 1.0 224 sm/s (high speed calibration) (See Section 4.5 for flow measurement ranges in different tube diameters) * sm/s: standard meter per second			
Parameters	Standard unit flow:	m³/h		
	Available units:	m³/min, l/min, l/s, cfm, kg/h, kg/min, kg/s		
	Standard velocity unit:	m/s		
Reference conditions	ISO1217, 20 °C, 1000 mbar (Standard-Unit) DIN1343, 0 °C, 1013.25 mbar (Norm-Unit)			
Principle of measurement	Thermal mass flow			
Sensor	Resistive sensor			
Measured medium	Air, gas (non corrosive gas)			
Operating temperature	-40 +150°C (Medium temperature) -40 +65°C (Ambient temperature)			
Humidity of the meas. medium	< 90%, no condensation			
Operating pressure	0 4.0 MPa (>1.6 MPa needs the installation device.)			
Housing material	Al alloy			
Material of the probe tube, sensor head and screwing	Stainless steel 1.4404 (SUS 316L)			
Protection class	IP67			
Dimensions	See dimensional drawing on the next page			
Display (optional)	128 x 64			
Tube diameter	From DN15 (1/2") upwards			



Screwing thread	G1/2" (ISO 228/1)
Weight	1.75 kg (220 mm version)

5.2 Electrical data

Power supply	16 30 VDC, 5 W

5.3 Output signals

Analog output	See section 9.1.1
Pulse output	See section 9.1.2
HART output	See section 9.2
Modbus output	See section 9.3
M-Bus output	See section 9.4

5.4 Accuracy

Accuracy*	±(1.5% of reading + 0.3% full scale)
Repeatability	0.25% of reading
Stated accuracy at	Ambient/process temperature 23°C±3°C Ambient/process humidity <90% Process pressure at 0.6 MPa

^{*} The specified accuracy is valid only within the minimum and maximum flow rates that are stated in section 5.5.

5.5 Flow ranges

The flow ranges are stated under the following conditions:

· Standard flow in air

• Reference pressure: 1000 hPa

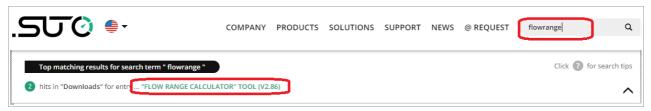
• Reference Temperature: +20°C



Inch	DN	S-Range (m³/h)	M-Range (m³/h)	HS-Range (m³/h)
1/2"	DN15	0.2 45.6	0.4 91.0	0.48 110.16
3/4"	DN20	0.4 89.1	0.9 177.8	1.09 215.3
1"	DN25	0.6 147.7	1.2 294.7	1.82 356.85
1 1/2"	DN40	1.5 366.7	2.9 731.9	4.36 886.18
2"	DN50	2.4 600	4.8 1198	7.26 1450.04
2 1/2"	DN65	4.1 1027	8.2 2049	12.1 2480.44
3"	DN80	5.7 1424	11.4 2841	16.94 3441.91
4"	DN100	8.7 2183	17.4 4357	24.2 5275.71
5"	DN125	20 3419.6	38 6824.4	45.9 8263.09
6"	DN150	20 4930	39 9839	70.18 11913.10
8"	DN200	35 8786	70 17533	106.48 21229.51
10"	DN250	55 13744	110 27429	165.77 33210.69
12"	DN300	79 19815	158 39544	239.58 47880.39

Remarks:

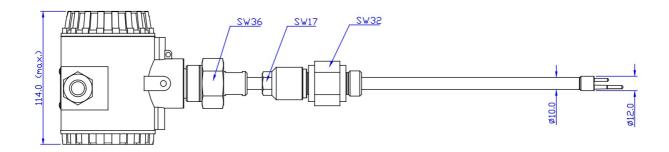
- To calculate flow ranges based on pipe and reference conditions in your site, download and install the "Flow range calculator" tool for free from http://www.suto-itec.com.
- To fast access the tool download page, enter "flowrange" (without spaces) in the search field, and click the tool in the search result.





6 Dimensional drawing







7 Determining the installation point

To maintain the accuracy stated in the technical data, the sensor must be inserted in the centre of a straight pipe section with unhindered flow characteristics.

Unhindered flow characteristics are achieved if the sections in front of the sensor (inlet) and after the sensor (outlet) are sufficiently long, absolutely straight and free of obstructions such as edges, seams, curves etc..

Please consider that enough space exists at your site for an adequate installation as described in this manual.



ATTENTION!

Wrong measurement may occur if the sensor is not installed correctly.

- Pay careful attention to the design of the inlet and outlet sections.
 Obstructions can cause counter-flow turbulence as well as turbulence in the direction of the flow.
- It is strongly recommend not to install S450 permanently in wet environment which exists usually right after a compressor outlet.



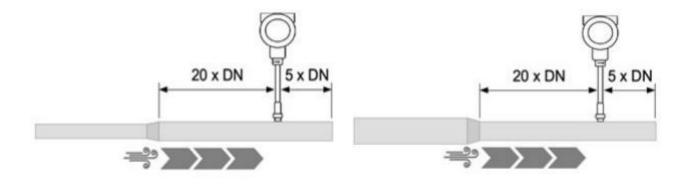
7.1 Inlet and outlet sections

The following figures show the necessary equalizing sections in relation to existing obstructions. If it is not possible to observe the indicated equalizing sections, deviations in measuring results have to be expected.

Remark: If there is any combination of below situations, the longest straight inlet section must be maintained.

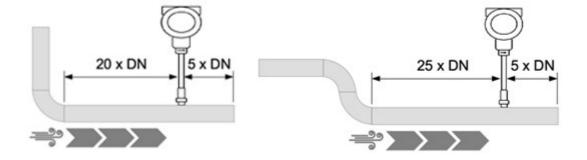
Expansion

Reduction



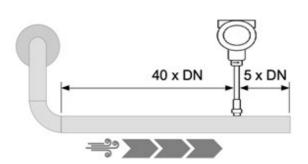
• 90° Bend

2×90° Bend

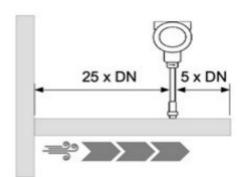




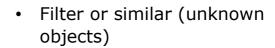
• 3 dimensional Bend

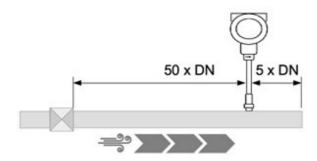


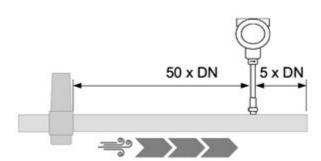
• T-piece



Shut-off valve







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8 Installation

Before installing the sensor, please make sure that all components listed below are included in your package.

Qty	Description	Item No.
1	Sensor	S695 0450
1	Sealing ring	No P/N
1	Alignment key	No P/N
1	G ½" ball valve	A554 0008
1	USB Bluetooth dongle	No P/N
1	USB disk(with the service Software stored)	No P/N
1	Instruction manual	No P/N
1	Calibration certificate	No P/N



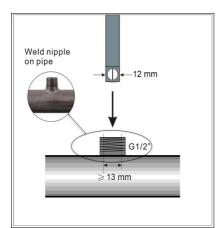
ATTENTION!

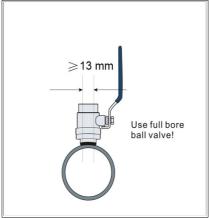
Do not insert the sensor with strong force. It may happen that the probe tip strikes on the pipe inner wall and causes the sensor damaged!

8.1 Installation requirements

To install the sensor a ball valve or a nozzle is needed.

- The inner thread must be G 1/2".
- The diameter of the hole must be ≥ 13mm. Otherwise the shaft can not be inserted in.





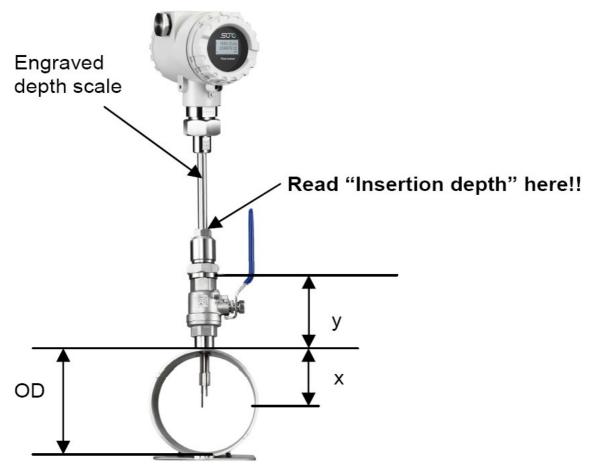


8.2 Installation procedure

The following steps explain the procedure of an appropriate installation.

8.2.1 Determining the insertion depth of the sensor

The probe tip must be placed in the center of the pipe. For this the probe shaft has a scale. To determine the right position please calculate the insertion depth as described below.



Insertion depth =
$$x + y$$

$$x = \frac{OD}{2}$$
; $OD = Outer diameter of pipe$

Example for a 2" pipe and an 87 mm ball valve:

$$y=87 \text{ mm}$$
; $OD=60.3 \text{ mm}$
 $x=\frac{OD}{2}=\frac{60.3 \text{ mm}}{2}=30.15 \text{ mm}$

Insertion depth = 30.15 mm + 87 mm = 117.15 mm



8.2.2 Installing the sensor



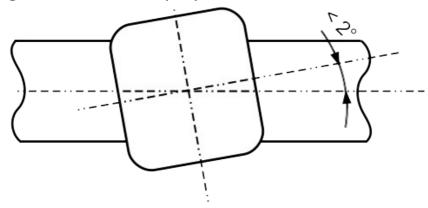
First please observe the flow direction indicated on the shaft. It must match the flow direction of the compressed air or gas.

- 1. Close the ball valve.
- 2. The probe tip must be be completely covered by the connection head (see photo on the left).
- 3. Underlay the "O-shaped" sealing ring to the groove in the connection head.
- 4. Screw the connection head tightly to the ball valve
- 5. Align the flow sensor with the flow direction by observing the flow direction indicated on the shaft.
- 6. Open the ball valve and tighten the clamp sleeve manually.
- 7. Move the flow sensor slightly to the determined insertion depth by means of the scale.
- 8. Tighten the clamp sleeve at the connection head so that the flow sensor can no longer be moved by the pressure in the pipe. However it should be possible to move the sensor shaft by hand.
- 9. With the aid of the alignment key, make sure that the actual flow direction is same as the arrow shown on the housing. (The angle deviation should not be larger than \pm 2° to the perfect position, please see picture on the next page.).
- 10. Tighten the clamp sleeve with the clamping torque 20 ... 30 Nm.
- 11. Check the installation depth again because sometimes the shaft is moved from its original position by the compressed air.





Maximum angle deviation of a proper installation:



8.2.3 Removing the sensor

- 1. Hold the flow sensor firmly.
- 2. Release the clamp sleeve from the connection head.
- 3. Pull out the shaft slowly until the value "10" can be read at the scale.
- 4. Close the ball valve.
- 5. Release the connection head and unscrew the flow sensor.

8.3 Electrical connection

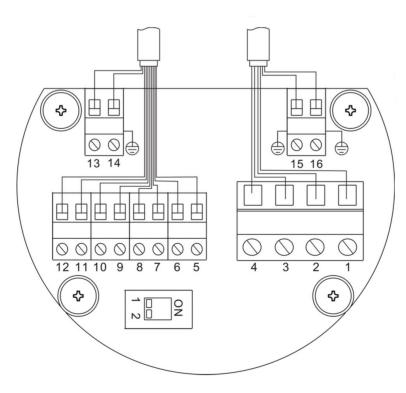
When installing the cables please consider following point:

- Keep the stripped and twisted length of cable shield as short as possible.
- Screen and ground the signal lines.
- Unused cable entries must be closed with closers.
- Cable outer diameter should be between 6 and 8 mm.
- Single wire cross-section should be between 0.25 ... 0.75 mm².
- The thread size for the cable glands is M20 / 1.5.



8.3.1 Connection diagram

Remove the back cover from the S450, and the pin layout is shown below.



8.3.2 Pin assignment

S450 provides four output options. The pin assignment of these options are given in the following table.

Pin	Output options					
PIII	Pulse and analog	Modbus	M-Bus	HART		
1	GND _{SDI}	GND_{SDI}	GND _{SDI}	GND _{SDI}		
2	+V _B	+V _B	+V _B	+V _B		
3	-V _B	-V _B	-V _B	-V _B		
4	SDI	SDI	SDI	SDI		
5	DIR	DIR	DIR	DIR		
6	DIR	DIR	DIR	DIR		
7	SW	SW	SW	NA		
8	SW	SW	SW	NA		
9	-I ₁	-I ₁	-I ₁	-I ₁ / -HART		



10	+I1	+I ₁	+I1	+I ₁ / +HART
11	-I ₂	+D	М	NA
12	+I2	-D	М	NA
13	NA	GND _м	NA	NA
14	Earth	Earth	Earth	Earth
15	Earth	Earth	Earth	Earth
16	Earth	Earth	Earth	Earth

Legend to pin assignment

= Digital signal (internal use) SDI SW = Isolated Pulse output $GND_{SDI} = Ground for SDI$ = Flow direction input DIR $+V_{R}$ = Positive supply voltage = Modbus data+ +D -V_B = Negative supply voltage = Modbus data --D $+ I_{1}$ = Positive signal output Μ = M-Bus data (analog output 1) = Negative signal output Not applicable $-I_{1}$ NA (analog output 1) $+I_{2}$ = Positive signal output (analog output 2) $-I_2$ = Negative signal output (analog output 2)



9 Signal outputs

9.1 Analog and pulse outputs

If the S450 is purchased with the output option of analog and pulse signals, it provides 2 analog outputs and 1 pulse output. All signals are electrically isolated.

9.1.1 Analog output

The analog output can be used as an active output (current is sourced through the positive connection pin) or passive output. In the passive configuration, a current signal is modulated into the external signal voltage.

Active : 4 to 20mA, RL < 400 Ω

Passive : 4 to 20mA, supply voltage 18 ... 30 VDC, RL < 500 Ω

For HART : $RL \ge 250 \Omega$

Uncertainly: < 0.3 % of reading

Resolution: 0.005 mA

9.1.2 Pulse output

No switch and polarity are required. Galvanic isolation.

Max. rating: 30 VDC, 200 mA

Pulse width: 10 ... 100 msec (depending on the flow rate)

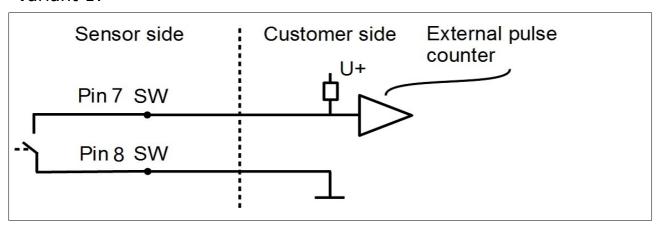
The maximum number of pulse per second is limited to 45. As a result, depending on the flow rate and the selected consumption unit, the maximum flow rates are listed in the following table.



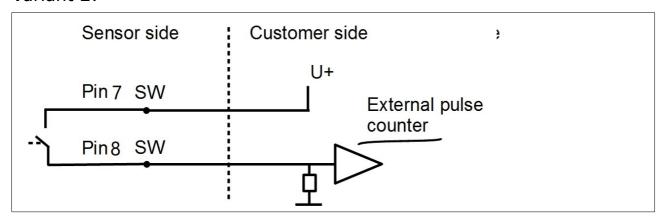
Pulse /	Max flow				
consumption unit	1/1	1/10	1/100		
m³/h	162,000	1,620,000	16,200,000		
m³/min	2,700	27,000	270,000		
l/min	2,700	27,000	270,000		
cfm	2,700	27,000	270,000		
Kg/h	162,000	1,620,000	16,200,000		
Kg/min	2,700	27,000	270,000		
Kg/s	45	450 4,500			
	Default	Configurable by service softwa			

Pulse connection diagram

Variant 1:



Variant 2:





9.2 HART output

If the S450 is purchased with the output option of HART, the HART signal is modulated on analog output 1. In case S450 is used in a multi-drop configuration (more than 1 salve on the 4-20 mA line) the analogue output can not be used anymore.

Device type : Slave

Polling address : 1 to 15

Bus address can be set through software

Physical interface : BELL 202

Protocol version : V 5.2 Tag : S450

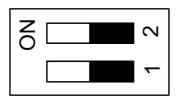
Tag description : Flow meter

Frame/parity/Stop: 8, 0, 1

9.3 Modbus output

If the S450 is purchased with the output option of Modbus, it provides one analog output and one pulse output.

The Modbus communication requires to activate terminal resistors at the last device on the bus system. If the S450 is the last device on the bus system, the DIP switches on the connector board should be set to "ON" position.



Termination resistor network switch

Device type : Slave

Address range : 1 to 251

Bus address can be set through software

Physical: RS485 in accordance with EIA/TIA-485 standard

interface

Baud rates : 1200, 2400, 4800, 9600, 19200, 38400, 57600,

115200 Baud

Transm. mode : ASCII, RTU

Response time : Direct data access = 0 to 255 ms (configurable)



Remark: Modbus communication settings can be changed by the service software.

Modbus holding register table

Channel description	Unit	Resolution	Format	Length	Modbus Register address
Velocity	m/s	0.1	FLOAT	4-Byte	0
Flow	m³/h	0.1	FLOAT	4-Byte	6
Consumption	m³	1	UNIT32	4-Byte	12
Reverse consumption	m^3	1	UNIT32	4-Byte	18
Medium temperature	°C	0.1	FLOAT	4-Byte	24
Ambient temperature	°C	0.1	FLOAT	4-Byte	36

Remarks:

Resolutions vary with the units, which you can configure using the service software.

In the response message that the device returns to the master:

- Function code: 03
- Byte order (32-bit data): MID-LITTLE-ENDIAN.

To properly decode the 4-byte float and unsigned integer data in the response message, the master must change the byte order from MID-LITTLE-ENDIAN to the order that it is using (LITTLE-ENDIAN or BIG-ENDIAN).

Byte sequencing for different byte orders are shown in the table:

Byte order	Byte sequencing (HEX)	Example
MID-LITTLE-ENDIAN (Read from the device)	ABCD	0x 0A 11 42 C5
LITTLE-ENDIAN	BADC	0x 11 0A C5 42
BIG-ENDIAN	CDAB	0x 42 C5 0A 11



9.4 M-Bus output

If the S450 is purchased with the output option of M-Bus, it provides one analog output and one pulse output besides the M-Bus output.

Device type :Slave

Address range :1 to 251

Bus address can be set through software

Physical interface :Meter-Bus, EN1434-3
Baud rates :300, 2400, 9600 Baud

Frame/parity/Stop: 8, E, 1

10 Configuration

S450 enables you to configure parameter settings according to on-site requirements. The table below gives an overview about the available settings.

Parameters	Available settings	Default
Measurement	Tube diameter Flow unit Consumption unit Reference conditions	54.0 m³/h m³ P _s = 1000 hPA
	Gas type selection Consumption counter Operation pressure Flow direction	T _s = 20°C Air 0 m ³ 0.6 MPa Standard
Analog output 1	Measurement channel Scaling Active / passive	Flow 4 mA: 0 m ³ /h 20 mA: max flow Active
Analog output 2	Measurement channel Scaling Active / passive	Medium Temperature 4 mA: -50°C 20 mA: 150°C Active
Pulse output	Pulse / Alarm Pulses per consumption unit	Pulse 1
HART	Fieldbus address	0



	Manufacturer ID Device type code	255 0
Modbus	Device address Baudrate Framing/parity/Stop bit Transmission mode	1 19200 8, N, 1 RTU
M-Bus	Address Manufacturer code Baudrate	0 END 300

To configure S450 settings, use the service software stored in the USB disk that comes with the delivery package.

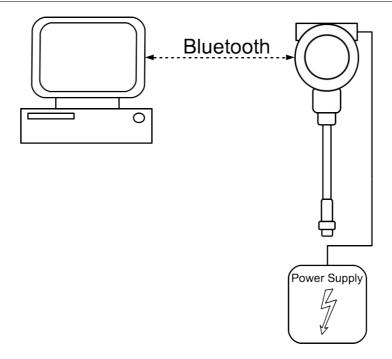
- 1. On a Windows® PC, insert the USB disk provided in the delivery package, and copy the service software file (Service Software S 450.EXE) to the PC and install it.
- 2. Power up the S450.
- 3. If the PC does not provide the Bluetooth interface, insert the USB Bluetooth dongle provided in the delivery package to the PC.
- 4. Pair the Bluetooth of the PC and the S450.
- 5. On the PC, run the service software and follow the onscreen instructions to complete the configuration. You can also refer to the online help file for more information.

Remark:

To enable a stable Bluetooth communication, ensure the following:

- Distance between the S450 and the PC must be not more than 5 meters.
- The PC Bluetooth antenna must point roughly at the direction of the display (front part).





11 Optional accessories

11.1 Sensor display

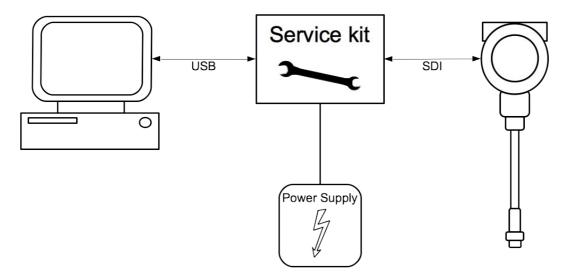
With the Sensor display it is possible to show the values of velocity, flow rate, consumption and error messages.

11.2 Service kit

The service kit is designed to enable the wired communication between the PC and an S450.

The diagram below shows the cable connection between an S450 and a PC through the service kit. Please ensure that S450 or the service kit is connected with the power supply because the USB port cannot provide enough power to both of them.





12 Calibration

Te sensor is calibrated ex work. The exact calibration date is printed on the certificate which is supplied together with the sensor. The accuracy of the sensor is regulated by the on site conditions, parameters like oil, high humidity or other impurities can affect the calibration and furthermore the accuracy. However we recommend to calibrate the instrument at least once per year. The calibration is excluded from the instruments warranty. For this please contact the manufacturer.

13 Maintenance

To clean the sensor it is recommended to use distilled water or isopropyl alcohol only. If the contamination can not be removed the sensor must be inspected and maintained by the manufacturer.

14 Disposal or waste



Electronic devices are recyclable material and do not belong in the household waste.

The device, the accessories and its packings must be disposed according to your local statutory requirements. The dispose can also be carried by the manufacturer of the product. Please contact the manufacturer for details.



15 Appendix - Modbus communication example

03 (0x03) Read holding register

Request Response

Slave address	1 byte	Slave address	1 byte
Function code	1 byte	Function code	1 byte
Starting address Hi	1 byte	Byte count	1 byte
Starting address Lo	1 byte	Register Hi	1 byte
No. of points Hi	1 byte	Register Lo	1 byte
No. of points Lo	1 byte	:	:
CRC	2 bytes	Register Hi	1 byte
		Register Lo	1 byte
		CRC	2 bytes

05 (0x05) Write single coil

Request Response

Slave address	1 byte	Slave address	1 byte
Function code	1 byte	Function code	1 byte
Coil address Hi	1 byte	Coil address Hi	1 byte
Coil address Lo	1 byte	Coil address Lo	1 byte
Data Hi	1 byte	Data Hi	1 byte
Data Lo	1 byte	Data L	1 byte
CRC	2 bytes	CRC	2 bytes



16 (0x10) Write multiple registers

Request Response

Slave address	1 byte	Slave address	1 byte
Function code	1 byte	Function code	1 byte
Starting address Hi	1 byte	Starting address Hi	1 byte
Starting address Lo	1 byte	Starting address Lo	1 byte
No. of registers Hi	1 byte	No. of registers Hi	1 byte
No. of registers Lo	1 byte	No. of registers Lo	1 byte
Byte count	1 byte	CRC	2 bytes
Data Hi	1 byte		
Data Lo	1 byte		
:	:		
Data Hi	1 byte		
Data Lo	1 byte		
CRC	2 bytes		

17 (0x11) Report slave ID

Request Response

Slave address	1 byte	Slave address	1 byte
Function code	1 byte	Function code	1 byte
CRC	2 bytes	Byte count	1 byte
		Slave ID	2 bytes
		Device run indicator	2 bytes
		Product code	2 bytes
		Product name	20 bytes
		CRC	2 bytes



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